three-point gripper HGDT-50-A Part number: 540868

Sturdy, can be used as internal and external gripper, for position sensing.



Data sheet

Feature	Value
Size	50
Stroke per gripper jaw	8 mm
Max. replacement accuracy	<= 0.2 mm
Max. angular gripper jaw backlash ax,ay	<= 0.1 deg
Max. gripper jaw backlash Sz	<= 0.05 mm
Rotationally symmetrical	<= 0.2 mm
Repetition accuracy, gripper	<= 0.03 mm
Number of gripper fingers	3
Assembly position	Any
Mode of operation	double-acting
Gripper function	3-point
Design structure	Inclined plane
	guided motion sequence
Position detection	For proximity sensor
Total force at 6 bar, opening	1,041 N
Total force at 6 bar, closing	921 N
Operating pressure	3 8 bar
Operating pressure, sealing air	0 0.5 bar
Max. operating frequency of gripper	<= 4 Hz
Min. opening time at 6 bar	85 ms
Min. closing time at 6 bar	75 ms
Operating medium	Compressed air in accordance with ISO8573-1:2010 [7:4:4]
Note on operating and pilot medium	Lubricated operation possible (subsequently required for further
	operation)
Corrosion resistance classification CRC	2 - Moderate corrosion stress
Ambient temperature	5 60 °C
Gripping force per gripper jaw at 6 bar, opening	347 N
Gripping force per gripper jaw at 6 bar, closing	307 N
Mass moment of inertia	11.05 kgcm2
Max. force on gripper jaw Fz static	1,500 N
Max. torque at gripper Mx static	50 Nm
Max. torque at gripper My static	30 Nm
Max. torque at gripper Mz static	40 Nm
Lubrication interval for guide components	5 Mio SP
Max. mass per external gripper finger	160 g
Product weight	1,104 g
Mounting type	With through-hole and dowel pin
	With internal thread and dowel pin
	Optional
Pneumatic connection, sealing air	M5
Pneumatic connection	G1/8
Materials note	Free of copper and PTFE
Material cover cap	High alloy steel, non-corrosive
Material housing	Wrought Aluminium alloy
	COMPCOTE coated
Material gripper jaws	Steel
	Hardened



FESTO